TRANSFORMER and Inductor design Handbook

Third Edition, Revised and Expanded

COLONEL WM. T. MCLYMAN Kg Magnetics, Inc. Idyllwild, California, U.S.A.

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To My Wife, Bonnie

Foreword

Colonel McLyman is a well-known author, lecturer, and magnetic circuit designer. His previous books on transformer and inductor design, magnetic core characteristics, and design methods for converter circuits have been widely used by magnetics circuit designers.

In this book, Colonel McLyman has combined and updated the information found in his previous books. He has also added several new subjects such as rotary transformer design, planar transformer design, and planar construction. The author covers magnetic design theory with all of the relevant formulas along with complete information on magnetic materials and core characteristics. In addition, he provides real-world, step-by-step design examples.

This book is a must for engineers working in magnetic design. Whether you are working on high "rel" state-of-the-art design or high-volume or low-cost production, this book is essential. Thanks, Colonel, for a well-done, useful book.

Robert G. Noah Application Engineering Manager (Retired) Magnetics, Division of Spang and Company Pittsburgh, Pennsylvania, U.S.A.

Preface

I have had many requests to update *Transformer and Inductor Design Handbook*, because of the way power electronics has changed over the past few years. This new edition includes 21 chapters, with new topics such as: The forward converter, flyback converter, quiet converter, rotary transformers, and planar transformers, with even more design examples than the previous edition.

This book offers a practical approach, with design examples for design engineers and system engineers in the electronics and aerospace industries. Transformers are found in virtually all electronic circuits. This book can easily be used to design lightweight, high-frequency aerospace transformers or low-frequency commercial transformers. It is, therefore, a design manual.

The conversion process in power electronics requires the use of transformers, components that frequently are the heaviest and bulkiest item in the conversion circuit. Transformer components also have a significant effect on the overall performance and efficiency of the system. Accordingly, the design of such transformers has an important influence on overall system weight, power conversion efficiency, and cost. Because of the interdependence and interaction of these parameters, judicious trade-offs are necessary to achieve design optimization.

Manufacturers have, for years, assigned numeric codes to their cores to indicate their power-handling ability. This method assigns to each core a number called the area product, A_p , that is the product of its window area, W_a , and core cross-section area, A_c . These numbers are used by core suppliers to summarize dimensional and electrical properties in their catalogs. The product of the window area, W_a , and the core area, A_c , gives the area Product, A_p , a dimension to the fourth power. I have developed a new equation for the power-handling ability of the core, the core geometry, K_g . K_g has a dimension to the fifth power. This new equation provides engineers with faster and tighter control of their design. It is a relatively new concept, and magnetic core manufacturers are now beginning to include it in their catalogs.

Because of their significance, the area product, A_p , and the core geometry, K_g , are treated extensively in this handbook. A great deal of other information is also presented for the convenience of the designer. Much of the material is in tabular form to assist the designer in making the trade-offs best suited for a particular application in a minimum amount of time.

Designers have used various approaches in arriving at suitable transformer and inductor designs. For example, in many cases a rule of thumb used for dealing with current density is that a good working level is 1000 circular mils per ampere. This is satisfactory in many instances; however, the wire size used to meet this requirement may produce a heavier and bulkier inductor than desired or required. The information

presented here will make it possible to avoid the use of this and other rules of thumb, and to develop a more economical and better design. While other books are available on electronic transformers, none of them seems to have been written with the user's viewpoint in mind. The material in this book is organized so that the student engineer or technician—starting at the beginning of the book and continuing through the end—will gain a comprehensive knowledge of the state of the art in transformer and inductor design.

No responsibility is assumed by the author or the publisher for any infringement of patent or other rights of third parties that may result from the use of circuits, systems, or processes described or referred to in this handbook.

Acknowledgments

In gathering the material for this book, I have been fortunate in having the assistance and cooperation of several companies and many colleagues. I wish to express my gratitude to all of them. The list is too long to mention them all. However, there are some individuals and companies whose contributions have been especially significant. Colleagues who have retired from Magnetics include Robert Noah and Harry Savisky, who helped so greatly with the editing of the final draft. Other contributions were made by my colleagues at Magnetics, Lowell Bosley and his staff for sending up-to-date catalogs and sample cores. I would like to thank colleagues at Micrometals Corp., Jim Cox and Dale Nicol, and George Orenchak of TSC International. I would like to give special thanks to Richard (Oz) Ozenbaugh of Linear Magnetics Corp. for his assistance in the detailed derivations of many of the equations and his efforts in checking the design examples. I also give special thanks to Steve Freeman of Rodon Products, Inc., for building and testing the magnetics components used in the design examples.

I am also grateful to: Dr. Vatche Vorperian of Jet Propulsion Laboratory (JPL) for his help in generating and clarifying equations for the Quiet Converter; Jerry Fridenberg of Fridenberg Research, Inc., for modeling circuits on his SPICE program; Dr. Gene Wester of JPL for his input; and Kit Sum for his assistance in the energy-storage equations. I also thank the late Robert Yahiro for his help and encouragement over the years.

Colonel Wm. T. McLyman

About the Author

Colonel Wm. T. McLyman recently retired as a Senior Member of the Avionics Equipment Section of the Jet Propulsion Laboratory (JPL) affiliated with the California Institute of Technology in Pasadena, California. He has 47 years of experience in the field of Magnetics, and holds 14 United States Patents on magnetics-related concepts. Through his 30 years at JPL, he has written over 70 JPL Technical Memorandums, New Technology Reports, and Tech-Briefs on the subject of magnetics and circuit designs for power conversion. He has worked on projects for NASA including the Pathfinder Mission to Mars, Cassini, Galileo, Magellan, Viking, Voyager, MVM, Hubble Space Telescope, and many others.

He has been on the lecture circuit for over 20 years speaking in the United States, Canada, Mexico, and Europe on the design and fabrication of magnetic components. He is known as a recognized authority in magnetic design. He is currently the President of his own company, Kg Magnetics, Inc., which specializes in power magnetics design.

He recently completed a book entitled, *High Reliability Magnetic Devices: Design and Fabrication* (Marcel Dekker, Inc.). He also markets, through Kg Magnetics, Inc., a magnetics design and analysis software computer program called "Titan" for transformers and inductors (see Figure 1). This program operates on Windows 95, 98, 2000, and NT.

Cadit	4	Analysis	Spec III
AC Inductor	Transformer	Mag Amp.	Coupled Ind.
DC Inductor	DC Inductor	Mag. Current	Sinewave Inverter
Transformer	AC Inductor	Short Circuit	Current Transformer
Fly	back	Spec 1	Spec II
Continuous	Discontinuous	Forward Conv.	Magnetic Equations
Boost	Boost	Three Phase	Resistor Trim
Buck	Buck		Com Mode Ind.
Buck/Boost Iso.	Buck/Boost Iso.	Mag Amp.	Single Layer Ind
Inv. Buck/Boost	Inv. Buck/Boost	DC Ind. Resistance	Low Current Ind.
Specia	lty tV −	Core Co	nversion
Air Core Rotary Transformer		Core Col	nversion

Figure 1. Computer Design Program Main Menu.

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Symbols

α	regulation, %
A _c	effective cross section of the core, cm ²
A _p	area product, cm ⁴
A _t	surface area of the transformer, cm ²
A_w	wire area, cm ²
$A_{w(B)}$	bare wire area, cm ²
$A_{w(l)}$	insulated wire area, cm ²
A_{wp}	primary wire area, cm ²
$\mathbf{A}_{\mathbf{ws}}$	secondary wire area, cm ²
A-T	amp turn
AWG	American Wire Gage
В	flux, tesla
B _{ac}	alternating current flux density, tesla
ΔB	change in flux, tesla
\mathbf{B}_{dc}	direct current flux density, tesla
B _m	flux density, tesla
B _{max}	maximum flux density, tesla
B _o	operating peak flux density, tesla
B_{pk}	peak flux density, tesla
B _r	residual flux density, tesla
B _s	saturation flux density, tesla
С	capacitance
C _n	new capacitance
C _p	lumped capacitance
СМ	circular mils
$\mathbf{D}_{\mathrm{AWG}}$	wire diameter, cm
D _(min)	minimum duty ratio
D _(max)	maximum duty ratio
D _x	dwell time duty ratio
Е	voltage
E_{Line}	line to line voltage
E_{Phase}	line to neutral voltage
Energy	energy, watt-second

ESR	equivalent series resistance
η	efficiency
f	frequency, Hz
F	fringing flux factor
$\mathbf{F}_{\mathbf{m}}$	magneto-motive force, mmf
F.L.	full load
G	winding length, cm
γ	density, in grams-per-cm ²
3	skin depth, cm
Н	magnetizing force, oersteds
H_{c}	magnetizing force required to return flux to zero, oersteds
ΔH	delta magnetizing force, oersteds
H _o	operating peak magnetizing force
Hs	magnetizing force at saturation, oersteds
Ι	current, amps
I _c	charge current, amps
ΔI	delta current, amps
I _{dc}	dc current, amps
I _{in}	input current, amps
I _{Line}	input line current, amps
I _{Phase}	input phase current, amps
Im	magnetizing current, amps
Io	load current, amps
I _{o(max)}	maximum load current, amps
I _{o(min)}	minimum load current, amps
Ip	primary current, amps
Is	secondary current, amps
I _{s(Phase)}	secondary phase current, amps
$I_{s(\text{Line})}$	secondary line current, amps
J	current density, amps per cm ²
K _c	copper loss constant
K _c	quasi-voltage waveform factor
K _e	electrical coefficient

K _f	waveform coefficient
K _g	core geometry coefficient, cm^5
K _j	constant related to current density
K _s	constant related to surface area
K _u	window utilization factor
K _{up}	primary window utilization factor
K _{us}	secondary window utilization factor
K _{vol}	constant related to volume
K _w	constant related to weight
L	inductance, henry
L _c	open circuit inductance, henry
L _p	primary inductance, henry
1	is a linear dimension
L _(crt)	critical inductance
λ	density, grams per cm ³
l_{g}	gap, cm
l _m	magnetic path length, cm
l _t	total path length, cm
mks	meters-kilogram-seconds
MLT	mean length turn, cm
mmf	magnetomotive force, F _m
MPL	magnetic path length, cm
mW/g	milliwatts-per-gram
μ	permeability
μ_{i}	initial permeability
μ_{Δ}	incremental permeability
μ_{m}	core material permeability
μο	permeability of air
μ _r	relative permeability
μ _e	effective permeability
n	turns ratio
N	turns
N.L.	no load

N _L	inductor turns
N _n	new turns
N _p	primary turns
N _s	secondary turns
Р	watts
P _{cu}	copper loss, watts
P _{fe}	core loss, watts
Pg	gap loss, watts
φ	magnetic flux
P _{in}	input power, watts
P _L	inductor copper loss, watts
Po	output power, watts
P _p	primary copper loss, watts
P _s	secondary copper loss, watts
\mathbf{P}_{Σ}	total loss (core and copper), watts
Pt	total apparent power, watts
P _{VA}	primary volt-amps
R	resistance, ohms
R _{ac}	ac resistance, ohms
R _{cu}	copper resistance, ohms
R _{dc}	dc resistance, ohms
R _e	equivalent core loss (shunt) resistance, ohms
R _g	reluctance of the gap
R _m	reluctance
R _{mt}	total reluctance
R _o	load resistance, ohms
R _{o(R)}	reflected load resistance, ohms
R _{in(equiv)}	reflected load resistance, ohms
R _p	primary resistance, ohms
R _R	ac/dc resistance ratio
R _s	secondary resistance, ohms
R _t	total resistance, ohms
ρ	resistivity, ohm-cm

S_1	conductor area/wire area
S_2	wound area/usable window
S ₃	usable window area/window area
S_4	usable window area/usable window area + insulation area
S_{np}	number of primary strands
S _{ns}	number of secondary strands
$\mathbf{S}_{\mathbf{V}\mathbf{A}}$	secondary volt-amps
Т	total period, seconds
t _{off}	off time, seconds
t _{on}	on time, seconds
t _w	dwell time, seconds
T _r	temperature rise, °C
U	multiplication factor
VA	volt-amps
V _{ac}	applied voltage, volts
V _c	control voltage, volts
$V_{c(pk)}$	peak voltage, volts
V _d	diode voltage drop, volts
\mathbf{V}_{in}	input voltage, volts
$V_{in(max)}$	maximum input voltage, volts
$V_{in(min)}$	minimum input voltage, volts
$\mathbf{V}_{\mathbf{n}}$	new voltage, volts
Vo	output voltage, volts
V _p	primary voltage, volts
V _{p(rms)}	primary rms voltage, volts
$V_{s(LL)}$	secondary line to line voltage, volts
$V_{s(LN)}$	secondary line to neutral voltage, volts
V _{r(pk)}	peak ripple voltage
Vs	secondary voltage, volts
ΔV_{CC}	capacitor voltage, volts
ΔV_{CR}	capacitor ESR voltage, volts
ΔV_p	delta primary voltage, volts
ΔV_s	delta secondary voltage, volts

W	watts
W/kg	watts-per-kilogram
Wa	window area, cm ²
W_{ap}	primary window area, cm ²
W _{as}	secondary window area, cm ²
W _{a(eff)}	effective window area, cm ²
W-S	watt-seconds
W _t	weight, grams
W _{tcu}	copper weight, grams
W _{tfe}	iron weight, grams
X _L	inductive reactance, ohms