Section I3: Feedback Amplifiers

We are now going to discuss two specific examples of voltage and current feedback using the common-emitter (emitter-resistor) amplifier configuration. The specific examples chosen were previously introduced in Section D8 (Chapter 7 of your text) when we discussed bias stability and types of biasing. Your author uses the CE (ER) amplifier since we can use the same circuit to investigate both feedback and no feedback operation by controlling the value of the emitter resistor bypass capacitor (this is also the configuration used in Section D8). Keep in mind that any of the BJT configurations we have been studying, in addition to op-amps, may employ any of the four feedback topologies presented in the previous section. Also, as I alluded to earlier, while amplifiers contain active elements, feedback networks are generally composed of passive elements. If frequency dependent components are used in the feedback network, the amount of feedback will be determined by the frequency of the input signals and, as the frequency changes, the amount of feedback changes.

Current Feedback-Voltage Subtraction (Series-Series)

The generic common-emitter amplifier stage is reproduced to the right (a slightly modified representation of Figure 11.3). For our purposes, we are going to assume that $C_B$ and $C_C$ are very large so that they appear as short circuits for frequencies of interest. By varying the value of the capacitor $C_E$, we can investigate the circuit behavior for the case of no feedback ($C_E$ large, $R_E$ shorted for ac signals) and for the case of feedback (in the extreme case, $C_E=0$ and acts like an open circuit – which we have been calling the emitter-resistor configuration).

The small signal model, with $C_B$ and $C_C$ shorted, but including $C_E$, is shown to the right (a modified version of Figure 11.4). As an aside, note that the feedback circuit (which is just the resistor $R_E$ in this case) is a series contribution to both the input and output circuits –
hence the **series-series** designation I confused the mess out of you with in the previous section.

Anyway, using the small signal circuit, we can see that the output voltage is

\[ v_{out} = -\beta i_b (R_C \ || \ R_L), \]

while the input voltage (note that the voltage across \( R_B \) is \( v_{in} \), so we don’t need to include it in the equation) is

\[ v_{in} = i_b r_x + \beta i_b (R_E \ || \ Z_{CE}) = \beta i_b [r_e + (R_E \ || \ Z_{CE})], \]

where the impedance of the capacitor, \( C_E \), is defined as \( Z_{CE} = 1/sC_E \) and we have assumed that \((\beta + 1) \approx \beta\). The voltage gain of the common-emitter stage now becomes a function of frequency and is given by

\[
A_v = \frac{v_{out}}{v_{in}} = \frac{-\beta i_b (R_C \ || \ R_L)}{\beta i_b [r_e + (R_E \ || \ 1/sC_E)]} = \frac{-R_C \ || \ R_L}{r_e + (R_E \ || \ 1/sC_E)}.
\]  

(Equation 11.4)

We can look at the two feedback extremes by making appropriate modifications to the capacitor impedance in Equation 11.4. The voltage gain with maximum feedback (i.e., the emitter-resistor configuration) is known as the **closed-loop gain** and is found by letting \( C_E \) go to zero or equivalently, letting \( Z_{CE} \) go to infinity (an open circuit), in Equation 11.4. The expression for the closed-loop gain then becomes

\[
A_{v(closed\ loop)} = \frac{-(R_C \ || \ R_L)}{r_e + R_E},
\]

(Equation 11.5, Modified)

which is just the gain expression for the emitter-resistor configuration. Note that your author has further simplified this relationship in the text version of Equation 11.5 by letting \( R_E \gg r_e \). While this may be true most of the time, I don’t really want to make a firm commitment – if it is true, it will be obvious and fall out in the math.

Similarly, the voltage gain without feedback (i.e., the common-emitter configuration) is designated the **open-loop gain** and is found by letting \( C_E \) go to infinity or equivalently, letting \( Z_{CE} \) go to zero (a short circuit), in Equation 11.4. If \( Z_{CE} \) is zero, the parallel combination of \( R_E \) and \( Z_{CE} \) is also zero and the open-loop gain is
\[ A_{v(open\ loop)} = \frac{- (R_C \ || \ R_L)}{r_e} = -g_m (R_C \ || \ R_L) = \frac{- \beta (R_C \ || \ R_L)}{r_\pi}, \]  

(Equation 11.6)

which is the gain expression for the common-emitter amplifier.

A couple of things to notice from Equations 11.4, 11.5 and 11.6:

- The closed-loop gain is much smaller than the open-loop gain since \( r_e + R_E >> r_e \).
- If \( R_E >> r_e \), the closed-loop gain expression does not include any transistor parameter values and the gain depends only on the ratio of external components. Contrast this with the open-loop gain (without feedback) that is dependent on the transistor parameters \( \beta \) and \( r_\pi \).
- Equation 11.4 is the most general form of closed-loop gain with feedback, where the amount of feedback depends on the frequency of operation (through the impedance of the capacitor).

Recall that the closed-loop transfer function of the model in the previous section was given by

\[ G(s) = \frac{G_o(s)}{1 + G_o(s)H(s)}, \]  

(Equation 11.3)

where \( G_o(s) \) was the open loop transfer function and \( H(s) \) was defined as the feedback factor. Associating parameters in the above expression with Equations 11.5 (or 11.4) and 11.6, we have

\[ G(s) = A_{v(closed \ loop)} = A_v \]
\[ G_o(s) = A_{v(open \ loop)} = A_{vo}, \]

where the frequency dependence is implied and the terms \( A_v \) and \( A_{vo} \) have been introduced to save typing (or writing). Rearranging Equation 11.4 (the most general feedback representation) to fit the form of Equation 11.3, we get

\[ A_v = A_{vo} \left\{ \frac{1}{1 + A_{vo}H} \right\} = \left( \frac{- (R_C \ || \ R_L)}{r_e} \right) \left\{ \frac{1}{1 + \left( -\frac{(R_C \ || \ R_L)}{r_e} \right) \left( -\frac{(R_E \ || \ Z_{CE})}{R_C \ || \ R_L} \right)} \right\}. \]
Prove to yourself that this actually works! The reason we’re making such a nice equation look so incredibly ugly is so we can pick off the term that corresponds to $H(s)$, or

$$H(s) = \frac{- (R_E \ || Z_{CE})}{R_C \ || R_L} = \frac{- (R_E \ || \frac{1}{sC_E})}{R_C \ || R_L}. \quad \text{(Equation 11.11)}$$

Note that your author refers to $H(s)$ as the feedback attenuation factor $\gamma$ (also called $\beta$ in many references) and defines this feedback factor in terms of the feedback voltage, $V_f$, to be

$$\gamma = \frac{V_f}{v_{\text{out}}} = \frac{- (R_E \ || Z_{CE})}{R_C \ || R_L}. \quad \text{(Equation 11.11)}$$

Using the expression for $v_{\text{out}}$, we can express the feedback voltage in terms of the collector current (remember we’re assuming $(\beta + 1) \approx \beta$ so $i_e \approx i_c = \beta i_b$) and the equivalent impedance in the emitter circuit as

$$V_f = \beta i_b (R_E \ || Z_{CE}),$$

which is the same quantity that reduces $v_{be}$ observed in the KVL of the base-emitter loop of Figure 11.4, or

$$v_{be} = v_{\text{in}} - i_e (R_E \ || Z_{CE}) \approx v_{\text{in}} - \beta i_b (R_E \ || Z_{CE}) = v_{\text{in}} - V_f.$$

Finally, we can express the general expression of gain with feedback found in Equation 11.4 in the form of Equation 11.3 as

$$A_v = \frac{A_{vo}}{1 + \gamma A_{vo}}. \quad \text{(Equation 11.12)}$$

Notice that since both $\gamma$ and $A_{vo}$ are negative, the loop gain $\gamma A_{vo}$ is positive – as it must be for negative feedback!

The sensitivity of an amplifier to changes in gain is determined by differentiating Equation 11.12 with respect to $A_{vo}$, or

$$\frac{dA_v}{dA_{vo}} = \frac{1}{(1 + \gamma A_{vo})^2}; \text{ or } dA_v = \frac{dA_{vo}}{(1 + \gamma A_{vo})^2}. \quad \text{(Equation 11.13, Modified)}$$
Dividing both sides by $A_v$ (as given in Equation 11.12), Equation 11.13 becomes

$$
\frac{dA_v}{A_v} = \left( \frac{dA_{vo}}{(1 + \gamma A_{vo})^2} \right) \frac{1 + \gamma A_{vo}}{A_{vo}} = \frac{dA_{vo}}{A_{vo} (1 + \gamma A_{vo})} \approx \frac{dA_{vo}}{\gamma A_{vo}^2}, \quad \text{(Equation 11.14)}
$$

where the last approximation was made by assuming that $\gamma A_{vo} >> 1$.

OK, great, what does this tell us? The ratio on the left hand side ($dA_v/A_v$) represents the variation in closed loop gain with respect to the nominal closed-loop gain value. The ratio on the (far) right hand side indicates that this is approximately equal to the change in open loop gain divided by $\gamma (A_{vo})^2$. Since $\gamma (A_{vo})^2$ is usually quite large, we can see that the variation in closed-loop gain is greatly reduced for a given variation in open-loop gain, or the closed loop gain becomes insensitive to changes in open loop gain.

*Now, wasn’t that worth it?*

**Voltage Feedback-Current Subtraction (Shunt-Shunt)**

The other form of feedback that we will be explicitly looking at was also introduced in Section D8 and is shown in Figure 11.5a (reproduced to the right). Here, we have replaced the $R_1$-$R_2$ combination that formed the base resistor, $R_B$, under ac conditions with a feedback resistor, $R_F$, which is tied between the base and collector of the BJT. For this form of feedback, the resistor $R_F$ “samples” the output voltage $v_o$ and feeds back a current that is then mixed with the source current. Since $v_o > v_{in}$, the current will flow as indicated in the figure above. For our purposes, we will assume that the capacitors $C_C$ and $C_E$ are sufficiently large so that they become short circuits at frequencies of interest.

*It appears that your author has renamed $v_{source}$ as $v_{in}$ in Figures 11.5a and 11.5b – I’m not sure why, but this is not valid unless $R_S$ is equal to zero. The resulting gain equations will be in the form of $v_o/v_S$ instead of $v_o/v_{in}$. If $v_o/v_{in}$ is desired, the input voltage divider will be required.*
The small signal circuit to the right contains the same information as Figure 11.5b in your text, but seems to be more in line visually with what we’ve been doing so far.

Writing a KCL at the base node,

\[ i_b = i_s + i_f = \frac{V_s - V_{\pi}}{R_s} + \frac{V_o - V_{\pi}}{R_F} = \frac{V_s}{R_s} + \frac{V_o}{R_F} - V_{\pi} \left( \frac{1}{R_s} + \frac{1}{R_F} \right) = \frac{V_s}{R_s} + \frac{V_o}{R_F} - \frac{V_{\pi}}{R_s || R_F} \]

Since \( i_b \) is also equal to \( v_o/r_{\pi} \), we may rewrite the above equation as

\[ i_b = \frac{V_s}{R_s} + \frac{V_o}{R_F} \frac{i_b r_{\pi}}{R_s || R_F} ; \quad i_b \left( 1 + \frac{r_{\pi}}{R_s || R_F} \right) = \frac{V_s}{R_s} + \frac{V_o}{R_F} ; \quad i_b = \frac{V_s}{R_s} + \frac{V_o}{R_F} \frac{\alpha}{r_{\pi}} \]

\[ \alpha = 1 + \frac{r_{\pi}}{R_s || R_F} \]  
(Equation 11.18)

Expressing the output voltage in terms of the base current as

\[ v_{out} = -\beta i_b (R_C || R_L) \]

and after much algebra (that I will provide if requested), the expression of Equation 11.19 is reached. I want to stress again that this relationship is a general expression of closed loop gain, but is in terms of \( v_o/v_s \) NOT \( v_o/v_{in} \). This is an acceptable strategy since the difference between the two is a resistive voltage divider that we are assuming is not frequency dependent, but be sure you know what you are actually calculating!

\[ A_v = \frac{V_o}{V_s} = \frac{-\beta (R_C || R_L)}{1 + \beta (R_C || R_L)/(\alpha R_F)} \]

(Equation 11.19, Modified)

To find the open-loop gain expression, let \( R_F \rightarrow \infty \) so that \( \alpha = 1 + r_o/R_s \).
\[ A_{vo} = \frac{-\beta (R_C \parallel R_L)}{R_S + r_x}. \]  
(Equation 11.20)

Following the same strategy as the earlier discussion, we can rewrite Equation 11.19 in the form of Equation 11.3 as

\[ A_v = \frac{A_{vo}}{1 + A_{vo} \left( \frac{-R_S}{R_F} \right)} = \frac{A_{vo}}{1 + \gamma A_{vo}}, \]  
(Equation 11.21)

where \( \gamma = -\frac{R_S}{R_F} \). Again, note that both \( \gamma \) and \( A_{vo} \) are negative so that the loop gain \( \gamma A_{vo} \) is positive and the closed-loop gain is less than the open-loop gain. Also, as \( A_{vo} \) becomes large, \( A_v \) approaches \( 1/\gamma = -R_F/R_S \), which is independent of transistor parameters.